

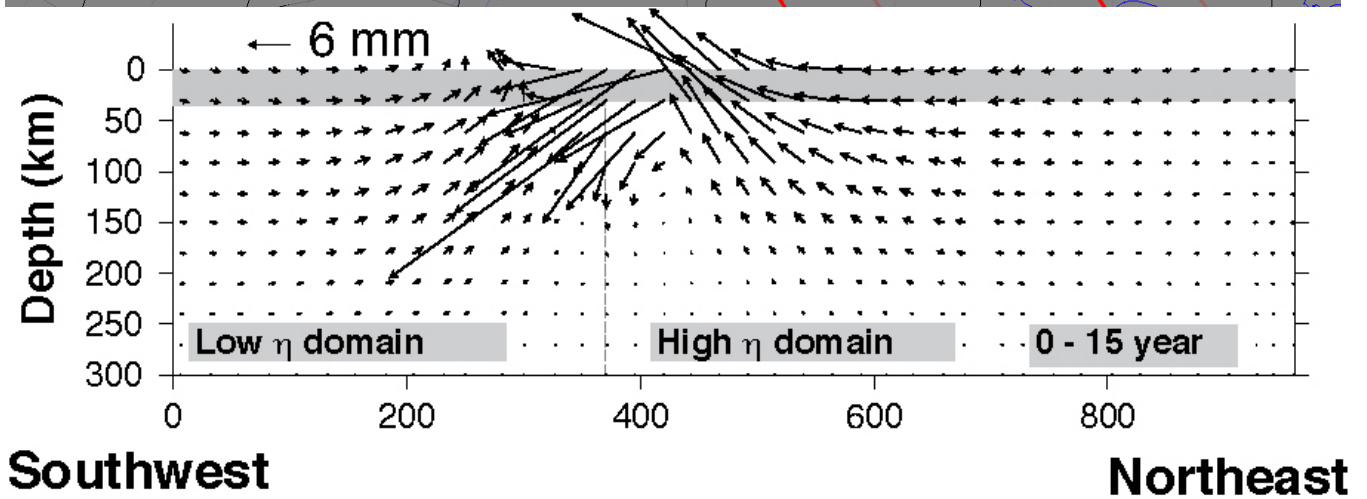
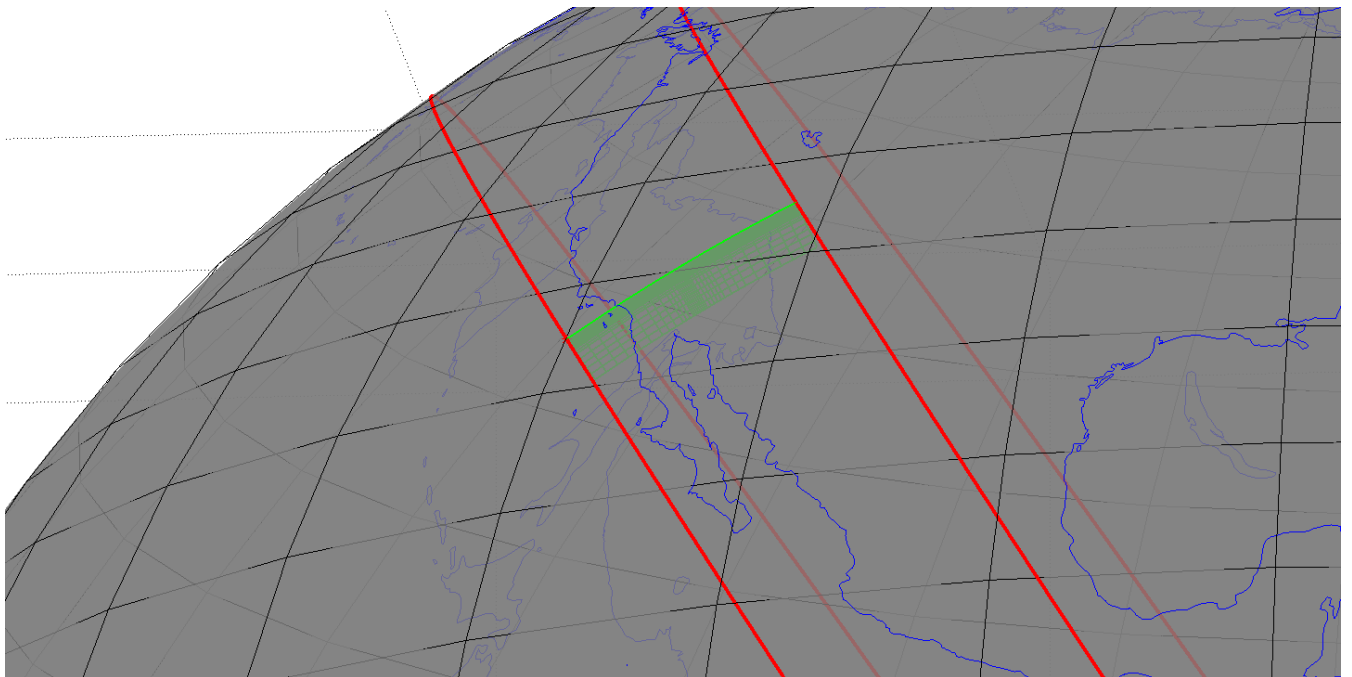
VISCO2.5D

Version 1.0 Tutorial

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1 Introduction

VISCO2.5D is a software package to calculate quasi-static deformation resulting from imposed earthquake sources in a spherical geometry. It solves the 3D equations of quasi-static equilibrium using the spectral element method (SEM) on a two-dimensional structure, with imposed source and domain boundary conditions. The viscoelastic structure is assumed to be azimuthally symmetric about a pole of symmetry (typically very distant from the model domain, in which case the structure practically varies in one horizontal Cartesian coordinate). In the spectral element domain, it produces time-dependent displacements at sets of points on Earth's surface and vertical profiles, as well as specified 'receiver' locations.

The program package is intended as a tool in modeling postseismic crustal deformation in the case that the sub-lithosphere rheology may be approximated with a linear stress-strain relation and the viscoelastic structure is two-dimensional. Such 2D structures would correspond to a contrast in material properties across, e.g. a long strike slip fault or a long convergent plate boundary with a dipping downgoing plate.

2 Description of program

The main program visco2pt5d is used for all steps of the computations needed to define a 2D global grid, specify a 2D viscoelastic structure, compute 3D postseismic displacements at various points in the model domain in the Laplace transform domain, and obtain time domain results.

Pollitz (2014) adapted the SEM of Komatitsch and Tromp (1999) for seismic wave propagation to the case of quasi-static motions. For the 2.5D problem, the approach is essentially that of Sinclair et al. (2007) adapted to the case of quasi-static deformation and a spherical geometry.

Following Pollitz (2014), the steps involved with calculating 2.5D quasi-static deformation are:

- (1) Define a 2D set of quadrilateral elements and derive a global indexing of this grid
- (2) Use the strong form of the equations of quasi-static equilibrium
- (3) Discretize the model
 - mesh of elements
 - obtain transformation between physical and local elemental coordinates
- (4) Interpolate functions on the elements
 - Lagrange polynomials
 - Gauss-Lobatto-Legendre (GLL) points
- (5) Integrate over individual elements
 - GLL integration quadrature
 - GLL points and weights
- (6) Define stiffness matrix
- (7) Assemble global linear system
- (8) Solve for displacements at the GLL points as a function of azimuthal order number
- (9) Perform weighted sum over azimuthal order, the weights depending on the azimuth of a given observation point
- (10) Inverse Laplace transform to obtain time domain results.

Generally, three runs of visco2pt5d in sequence accomplish these steps. The first run accomplishes step (1), the second run steps (2) through (8), and the third run steps (9) and (10).

We work in a $r - \theta - \phi$ spherical coordinate system (hereafter 'model coordinates'). A 2D spectral element domain is defined with respect to spherical coordinates of radius r and angular distance θ from a pole of symmetry P . Laterally variable 3D viscoelastic structure depends only upon r and θ , i.e., it is azimuthally symmetric. A seismic point source is implemented with an assumed periodicity in longitude ϕ with respect to P . The computational domain occupies a vertical slice bounded by a spherical shell at depth, the free surface, and vertical surfaces at two given angular distances from P .

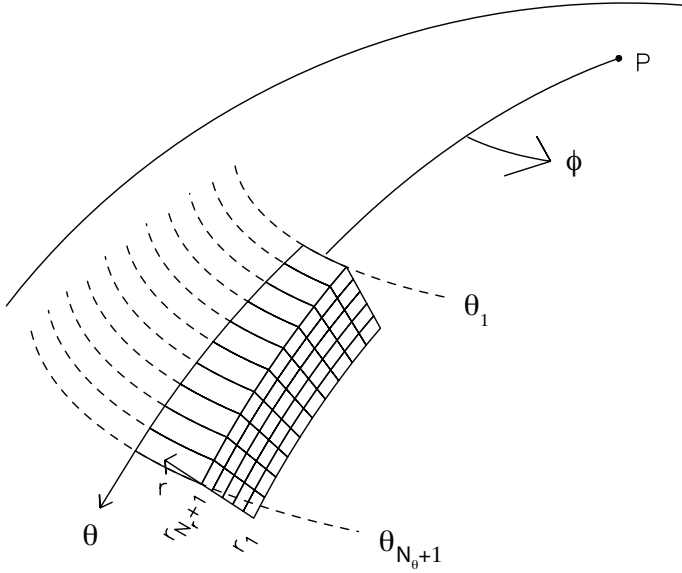


Figure 1. Geometry of model domain in 2.5D. Viscoelastic structure is assumed symmetric with respect to a symmetry pole P, i.e., it does not vary with ϕ , but may vary with θ and r . There are N_θ and N_r divisions of the model domain in the θ and r coordinates, respectively. Figure 1 of Pollitz (2014).

The viscoelastic structure and corresponding 2D GLL grid used in a typical run (e.g. Example 1 of this tutorial) looks like

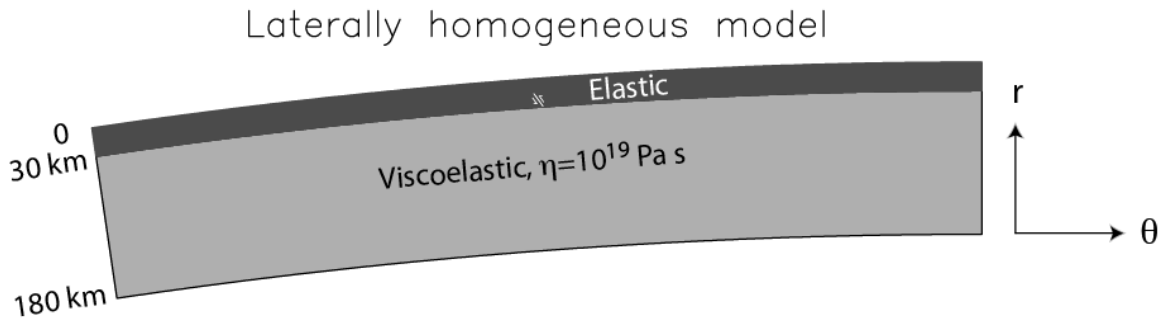


Figure 2. Definition of a 2D model domain into an elastic upper layer underlain by a viscoelastic medium.

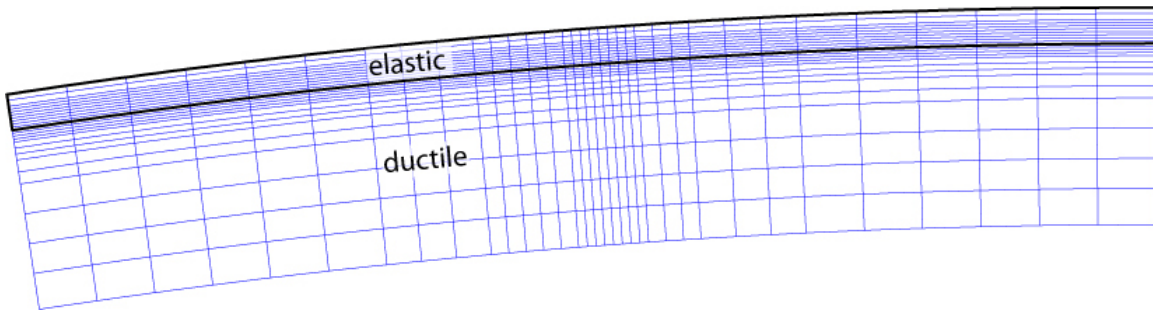


Figure 3. Division of 2D model domain into elements that are rectangular in r - θ space.

The present implementation uses rectangles in r - θ space to represent individual elements, i.e., different radius levels are separated by spherical shells, and angular distances are discretized with

the same spacing regardless of radius.

An individual element is discretized with GLL points, which serve as both collocation points for displacement and interpolation points for integrating the weighted equations of equilibrium over an element. For example, for 1D GLL functions of order $N=5$ in one dimension, the 2D GLL Cartesian grid looks like

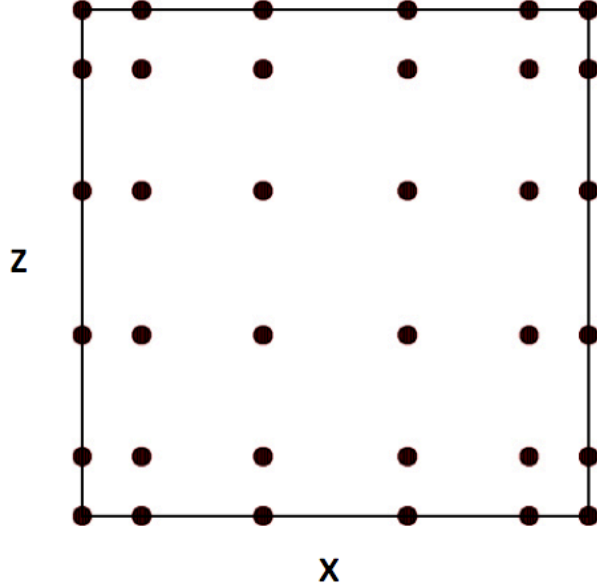


Figure 4. 2D GLL interpolation and quadrature points of one element.

There is a simple mapping between (x,z) in elemental coordinates and (θ,r) in physical spherical coordinates (eqns 17 and 18 of Pollitz, 2014). If there are $N+1$ points on the side of an element, then there are altogether $(N N_r + 1)(N N_\theta + 1)$ points in the global domain.

The equations of quasi-static equilibrium are formulated in the Laplace transform domain in order to facilitate the implementation of an assumed linear viscoelastic rheology. Letting s represent the Laplace transform parameter, the Burgers body rheology is represented with s -dependent bulk modulus κ_1 equal to the elastic bulk modulus κ and s -dependent shear modulus given by

$$\mu(s) = \frac{\mu_1 s \left(s + \frac{\mu_2}{\eta_2} \right)}{\left[\left(s + \frac{\mu_2}{\eta_2} \right) \left(s + \frac{\mu_1}{\eta_1} \right) + s \frac{\mu_1}{\eta_2} \right]}$$

κ_1, μ_1 η_1

Maxwell element

μ_2

η_2

Kelvin element

where μ_1 and μ_2 are the shear modulus of the Maxwell and Kelvin elements, respectively, and η_1 and η_2 are the viscosity of the Maxwell and Kelvin elements, respectively.

The displacement field $u(r, \theta, \phi; s)$ for a given s is parameterized with expansion coefficients evaluated at the 2D GLL collocation points. This displacement field depends on model radius r , colatitude θ , and longitude ϕ .

Assuming there is a global mapping between local coordinates x,z in an element and latitude and

longitude in global model coordinates, the ϕ dependence is realized with a sum over azimuthal order number m .

$$\mathbf{u}(r, \theta, \phi; s) = \sum_{m=-\infty}^{\infty} \sum_{\alpha=0}^N \sum_{\beta=0}^N \left[a_{\alpha\beta}^m(s) \psi_{\alpha\beta}(x, z) \hat{\boldsymbol{\theta}} + b_{\alpha\beta}^m(s) \psi_{\alpha\beta}(x, z) \hat{\boldsymbol{\phi}} + c_{\alpha\beta}^m(s) \psi_{\alpha\beta}(x, z) \hat{\mathbf{r}} \right] e^{im\phi} \quad (1)$$

where

$$(a_{\alpha\beta}^m, b_{\alpha\beta}^m, \text{ and } c_{\alpha\beta}^m)$$

are expansion coefficients for displacement and the Ψ -functions are 2D GLL functions, e.g. Appendix A of Pollitz (2014).

There are three sets of displacement expansion coefficients, one for each of the local unit vector directions at a given location. Thus there are altogether $3(N N_r + 1)(N N_\theta + 1)$ unknown expansion coefficients. The linear system of simultaneous equations that results from manipulating the strong form of the equations of quasi-static equilibrium is derived in Pollitz (2014). For a given Laplace transform parameter, this system is solved for these expansion coefficients.

At the GLL points themselves,

$$\psi_{\alpha\beta}(x_\gamma, x_\nu) = \delta_{\alpha\gamma} \delta_{\beta\nu} \quad (2)$$

so that the displacement field at GLL points $(\mathbf{r}_{\gamma\nu}, \theta_{\gamma\nu})$ and arbitrary ϕ is

$$\mathbf{u}(r_{\gamma\nu}, \theta_{\gamma\nu}, \phi; s) = \sum_{m=-\infty}^{\infty} \left[a_{\gamma\nu}^m(s) \hat{\boldsymbol{\theta}} + b_{\gamma\nu}^m(s) \hat{\boldsymbol{\phi}} + c_{\gamma\nu}^m(s) \hat{\mathbf{r}} \right] e^{im\phi} \quad (3)$$

Equation (1) is used by visco2pt5d to output static and time-dependent postseismic displacements at Earth's surface or at selected receiver points.

Equation (3) is used by visco2pt5d to output static and time-dependent postseismic displacements on a vertical profile along a chosen arc of constant longitude (presently, this is hardwired in the source code to be the arc $\phi=0$).

3 Checklist of input parameters

All of the information below must be specified in the various input files used in VISCO2.5D.

Earth model

- Viscoelastic structure as a function of depth and one lateral distance: density ρ , seismic wavespeeds V_p and V_s (equivalent to bulk modulus κ and shear modulus of Maxwell element μ_1), shear modulus of Kelvin element μ_2 , Maxwellian viscosity η_1 , and Kelvin viscosity η_2 as a function of radius. μ_2 is prescribed indirectly through the strength construct $\mu' = \mu_1 \mu_2 / (\mu_1 + \mu_2)$
- Radius of Earth

Source model

- Number of fault planes
- Strike, dip, rake, slip, length, depths of upper and lower fault edges, latitude and longitude of one fault corner
- Earthquake origin time; start and end times of cumulative postseismic displacements
- (Optional) Observation points to output displacements - in addition to GLL points**
- Number of observation points
- Latitude, longitude, and depth of these observation points

Model domain

- Number of elements in horizontal and radial directions
- dimensions of elements
- Spacing of fictitious sources; minimum wavelength in azimuthal coordinate

4 Compiling

Folders AMD, Suitesparse, and UMFPACK comprise the linear algebra package needed to compile VISCO2PT5. They are in the VISCO2.5D folder. These were originally obtained as the package SuiteSparse v4.4.4 downloaded from

<http://faculty.cse.tamu.edu/davis/suitesparse.html>

This package is due to Timothy A Davis: <http://faculty.cse.tamu.edu/davis/publications.html>

The configuration file VISCO2.5D/ SuiteSparse_config/SuiteSparse_config.mk has been modified for our application. In particular, it opts to not use LAPACK or BLAS subroutines, which as a result makes the linear algebra package run slower than it is capable of running. However, if speedups are desired, these may be accomplished later by modifying the options in this file. Note that many of the directories in VISCO2.5D/Suitesparse are not needed to compile visco2pt5d, but they are retained in case such speedups are desired at a later time.

gfortran must be installed in order to compile libraries and main programs.

AMD, Suitesparse, and UMFPACK libraries need to be compiled before the main program can be compiled. The names of the desired libraries are

VISCO2.5D/Suitesparse/AMD/Lib/libamd.a

VISCO2.5D/Suitesparse/SuiteSparse_config/libsuitesparseconfig.a

VISCO2.5D/Suitesparse/UMFPACK/Lib/libumfpack.a

- Compile AMD, Suitesparse, and UMFPACK libraries.

Change directory to VISCO2.5D/MAINPROG

Type 'make libs'

- Compile visco2pt5d

In VISCO2.5D/MAINPROG

Type 'make visco2pt5d'

The above make is for 64 bit. You may need to type in

make umf4_f77zwrapper64.o

before you try

make visco2pt5d

5 Examples

The examples given here are abbreviated descriptions of how to compute post-earthquake deformation for single-plane ruptures. Before running the examples, compile visco2pt5d as directed above.

5.1 Example 1

This example will do all of the calculations necessary to replicate Figure 6-8 of Pollitz (2014), which evaluates post-strike-slip faulting displacements generated by a 50 km-long vertical fault occupying the lower portion of the elastic layer on a spherically-layered model. This model has a prescribed Maxwell viscoelastic asthenosphere below an elastic lithosphere. Results include the $t = 1, 2$, and 5τ curves of Pollitz (2014, Figure 8), where τ is defined as $\tau = 2 \eta_1 / \mu_1$.

To run this example, run the command file `example1.x`, which contains the lines

```
#!/bin/bash
#
export VISCODIR=/home/cig/VISCO2.5D
export EXDIR=$VISCODIR/MAINPROG
export WORKDIR=$VISCODIR/Work
export WORKDIR1=$VISCODIR/Work1
#
cp elastic.paramEX1-Maxwell $WORKDIR/elastic.param
cp simulation-spherical.infoEX1 $WORKDIR/simulation-spherical.info
cp source-spherical.paramEX1 $WORKDIR/source-spherical.param
cp $EXDIR/visco2pt5d $WORKDIR/.

cd $WORKDIR
rm sporder.out
./visco2pt5d << !
1
!

date > $WORKDIR1/visco2pt5d-progress1.txt

cp $WORKDIR/elastic.param $WORKDIR1/.
cp $WORKDIR/simulation-spherical.info $WORKDIR1/.
cp $WORKDIR/source-spherical.param $WORKDIR1/.
cp receivers-latlondepEX1.txt $WORKDIR1/receivers-latlondep.txt
cp $EXDIR/visco2pt5d $WORKDIR1/.

cd $WORKDIR1
ln -sf $WORKDIR/sporder.out sporder.out
cp $WORKDIR/receivers-latlondep.txt receivers-latlondep.txt
./visco2pt5d << ! > /dev/null
0
rec-j-m1
displ-j-m1
```


visco2pt5d-progress1.txt

0. 1.00

!

cd \$WORKDIR

cp \$WORKDIR1/vertp-j vertp-j

cp \$WORKDIR1/rec-j-m1 rec-j-m

cp \$WORKDIR1/displ-j-m1 displ-j-m

./visco2pt5d << ! > /dev/null

2

not-needed

not-needed

not-needed

0. 1.00

!

#

mv visco2pt5d-stat_vertp.gmt visco2pt5d-stat_vertp-EX1.gmt

mv visco2pt5d-stat-rec.gmt visco2pt5d-stat-rec-EX1.gmt

mv visco2pt5d-post_vertp.gmt visco2pt5d-post_vertp-EX1.gmt

mv visco2pt5d-post-rec.gmt visco2pt5d-post-rec-EX1.gmt

mv visco2pt5d-stat-phival.gmt visco2pt5d-stat-phival-EX1.gmt

mv visco2pt5d-post-phival.gmt visco2pt5d-post-phival-EX1.gmt

Explanation of example1.x:

The first line, which specifies VISCODIR, sets the path to the top directory, i.e. the VISCO2.5D directory. 'example1.x' (and similarly 'example2.x' and 'example3.x') must be edited and this first line changed to the appropriate directory on the user's machine, i.e., where the VISCO2.5D directory resides.

EXDIR is the directory where a compiled version of visco2pt5 resides.

WORKDIR are WORKDIR1 are working directories where visco2pt5d is executed.

In a first step, relevant input files are copied to the WORKDIR directory. Then visco2pt5d is run in the WORKDIR directory with '1' in standard input. This tells it to only work on various indexing arrays that define the global grid.

In a second step, relevant input files are copied to the WORKDIR1 directory. Then visco2pt5d is run in the WORKDIR1 directory with '0' in standard input. This generates displacements of several types in the Laplace transform domain. This includes deformation at a specified set of receivers, on a vertical profile corresponding to azimuth=0 in model coordinates, and on Earth's surface.

In a third step, several files which contain Laplace-transformed displacements are copied from the WORKDIR1 directory to the WORKDIR directory. Then visco2pt5d is run in the WORKDIR directory with '2' in standard input. This converts the Laplace-transformed displacements to

time-dependent displacements and written to various output files which are finally in the WORKDIR directory.

visco2pt5d-stat_vertp.gmt has static displacements on a vertical profile corresponding to azimuth=0 in model coordinates.

visco2pt5d-stat-rec.gmt has static displacements at the receiver points.

visco2pt5d-stat-phival.gmt gmt has static displacements at a set of points on Earth's surface that encompasses the azimuth=0 in model coordinates.

visco2pt5d-post-rec.gmt has postseismic displacements at the receiver points. These are the post seismic cumulative displacements from time 0 up to a set of ten times following the synthetic earthquake.

visco2pt5d-post_vertp.gmt has postseismic displacements on a vertical profile corresponding to azimuth=0 in model coordinates. These are the post seismic cumulative displacements up to a set of ten times following the synthetic earthquake.

visco2pt5d-post-phival.gmt gmt has postseismic displacements at a set of points on Earth's surface that encompasses the azimuth=0 in model coordinates. These are cumulative postseismic displacements from time 0 up to times 1, 2, ..., 5τ after the synthetic earthquake.

In a final step, these output files are moved to files with names designating Example 1.

Note that the computed static displacements are generally not going to be accurate because the minimum wavelength of the computation of 30 km (specified in **simulation-spherical.info** in this example) is too long for the static displacement field, but this minimum wavelength is sufficient for the post-earthquake relaxation calculations.

Explanation of input files:

(1) Annotated version of **simulation-spherical.infoEX1**, including the format of viscoelastic model parameter file **elastic.paramEX1-Maxwell**

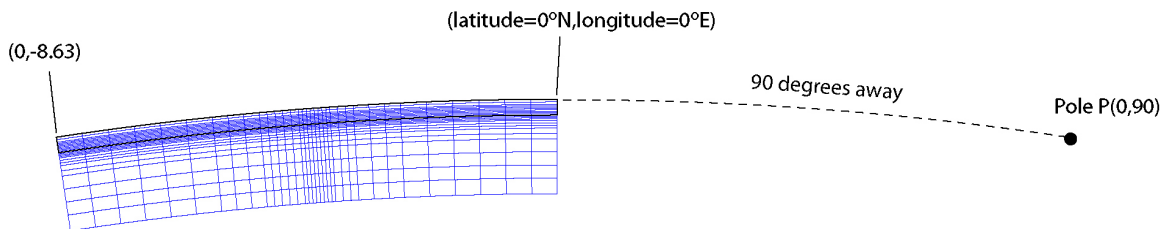


Figure 5. 2D model domain (in blue) and geometry specified in **simulation-spherical.infoEX1**.

[The model domain is essentially bounded by two small circles centered on a pole prescribed by the first two input lines (as well the radial dimension as prescribed in input lines 5-6).

In this file the pole is located 90 degrees away from (0.0N,0.0E) at an azimuth of 90 deg. from that point. This pole is located at $P=(0.0,90.0E)$.]

geographic coordinates of (theta,phi)=(theta_ref,0.) of spherical geometry in (deg.,deg.)
0. 0.

Angular distance theta_ref (geocentric deg.) and azimuth (deg. CW from due N) of pole from the above point
90. 90.

number of cells in theta^'-direction
34

[The first small circle is defined as being 90 geocentric degrees away from P.
The second small circle is defined as being 90 geocentric degrees + SUM_T radians away from P, where SUM_T is the sum of the 34 spherical-surface cell dimensions given below.
This turns out to be SUM_T = 0.150682688 radians = 8.63348198 degrees. So the second small circle is 90 + 8.63348198 = 98.63348198 degrees from P.]

theta-length of each cell (radians)
7.8480615e-3 7.8480615e-3 7.8480615e-3 7.8480615e-3 7.8480615e-3 7.8480615e-3
4.7088369e-3 4.7088369e-3 4.7088369e-3 2.354418e-3 2.354418e-3 2.354418e-3 1.17720e-3
1.17720e-3 1.17720e-3 1.17720e-3 1.17720e-3 1.17720e-3 1.17720e-3 1.17720e-3 2.354418e-3
2.354418e-3 2.354418e-3 2.354418e-3 2.354418e-3 4.7088369e-3 4.7088369e-3 4.7088369e-3
7.8480615e-3 7.8480615e-3 7.8480615e-3 7.8480615e-3 7.8480615e-3 7.8480615e-3
number of cells in z-direction
23

[There are 23 cells in the radial direction, going from a depth of SUM_Z to earth's surface, where SUM_Z is the sum of the 23 radial cell dimensions given below.
This yields SUM_Z = 180 km, corresponding to a radius of 6371 - 180 = 6191 km.
The cell size is taken larger at greater depth, i.e. the first one in the radial dimension goes from 180 to 150 km depth, the next from 150 to 125 km, the next from 125 to 100 km, etc.
Note that the actual computational domain is 2D
and goes from 0 to 0.150682688 radians in theta and 6191 to 6371 km in radius.
The theta computational domain is best thought of as being along an azimuth $\phi=0$ defined by the great circle connecting P with the given point (0.0N,0.0E) on the first small circle.
This great circle intersects the second small circle at (0.0N,-8.63348198E). So the 2D computational domain is bounded - in theta - by an arc connecting (0.0N,0.0E) with (0.0N,-8.63348198E) and - in radius - by spherical shells at 180 and 0 km depth.]

z-length of each cell (km)
30. 25. 25. 25. 10. 10. 5. 5. 5. 2.5 2.5 2.5 2.5 2.5 2.5 2.5 2.5 2.5 2.5 5.0 5.0
Effective width of third (i.e. phi) dimension (km); minimum wavelength in third dimension (km)

[For computational speedup, we suppose that there are sources evenly distributed in azimuth from P; the spacing between successive sources is 1200 km. This implemented in a spherical geometry by stepping in azimuthal order number by an amount approximately equal to $\text{twopi} * 6371 \text{ km} / (1200 \text{ km} * \sin(90. \text{ deg.})) = 33$. Similarly, with the 20. km minimum wavelength prescribed below, the maximum azimuthal order number used in the computation is $\text{twopi} * 6371 \text{ km} / (30 \text{ km} * \sin(90. \text{ deg.})) = 1333$. The minimum azimuthal order number is 0.]

1200. 30.
input file with elastic parameters

[This file has pointwise values of seismic velocities and Maxwell-solid parameters with the format

theta (deg.)	r-6371. (km)	Vp (km/s)	Vs (km/s)	Rho (g/cm ³)	\mu' (10 ^{10} Pa)	\eta_2 (10 ^{18} Pa s)	\eta_1 (10 ^{18} Pa s)
0.0000	-180.0000	5.4772	3.1623	3.0000		0.100000E+02	
0.0000	-177.0002	5.4772	3.1623	3.0000		0.100000E+02	
0.0000	-174.0004	5.4772	3.1623	3.0000		0.100000E+02	

(sample lines)

theta is measured positive from (0.0N,0.0E) along the great circle connecting P and that point, i.e., along the azimuth 90-180 = -90 deg. from (0.0N,0.0E). So theta=8.63348198 degrees corresponds to the point (0.0N,-8.63348198E).

r-6371 is 0 at earth's surface and -180 at the base of the computational model domain. The example file 'elastic.paramEX1-Maxwell', which is copied to elastic.param prior to running the main program, may permissibly go further down than 180 km. A simple scheme for identifying the closest point in this input file is used to assign viscoelastic parameters to the GLL points.

Vp and Vs are P-wave and S-wave isotropic seismic velocities; Rho is density.

For a Burgers body, η_2 and μ_2 are the viscosity and shear modulus of the Kelvin element (transient viscosity and shear modulus), and η_1 and μ_1 are the viscosity and shear modulus of the Maxwell element

(steady state viscosity and shear modulus). The seismic velocities and rho together determine the elastic bulk modulus and shear modulus μ_1 . μ' is defined as

$$\mu' = (\mu_1 * \mu_2) / (\mu_1 + \mu_2).$$

Note that for a Maxwell solid, one can either assign $\mu' = \mu_1$, $\eta_2 = \text{arbitrary}$, and $\eta_1 = \text{Maxwell viscosity}$ or equivalently, assign $\mu' = 0$, $\eta_1 = \text{very large}$, and $\eta_2 = \text{Maxwell viscosity}$, or, as is done in the example file, omit μ' and η_2 and provide only η_1 .]

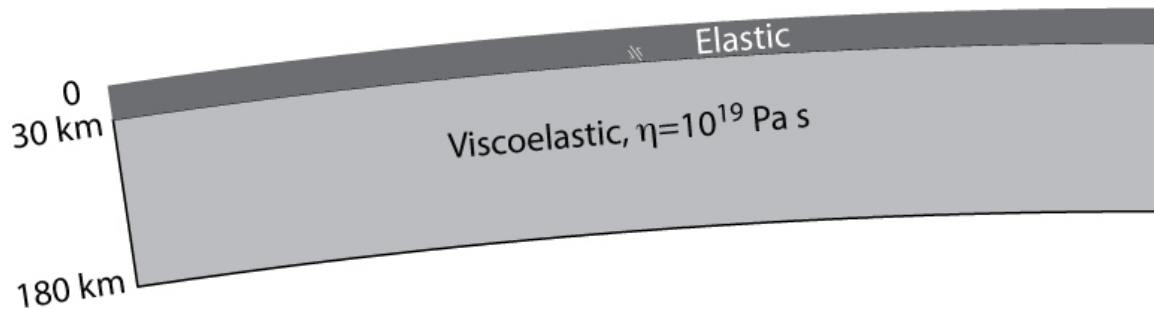


Figure 6. Laterally homogeneous model used in Example 1.

elastic.param

gravitational acceleration at earth's surface (m/s) (0 for non-gravitational case)

[In computations without gravitation, this is set to 0; in computations with gravitation, this is set to 9.8]

0.

(2) Annotated version of **source-spherical.paramEX1**

[cumulative postseismic displacements are evaluated in most cases from time t_1 to t_2 from an earthquake source at time t_0 , where t_0 is the year of earthquake, t_1 is the year obs. #1, and t_2 is year obs. #2. The viscosity multiplier has the effect multiplying all viscosities in the prescribed viscoelastic model by the given number. It is set to unity in these examples.]

year of earthquake, year obs.#1, year obs.#2 (yrs), viscosity multiplier

1975. 1975. 1996. 164 1.

finite fault with # segments

1

max depth, min depth (km), dip(deg.)
lat,lon(deg.),length(km),strike(deg.),rake(deg.),slip(cm) for each segment
29.00 15.00 90.
0.1589861 -4.15000 50. 45. 180. 100.

[This last line specifies the fault geometry of a dislocation plane.
The lower edge depth is 29.00 km, upper edge depth is 15.00, dip=90 deg.
30.1589861 -4.15000 is the lat,lon of the point on the lower edge of the fault closest to the strike direction, which is 45 deg.= N45E. That is, it is the northernmost point on the lower edge.
The fault length is 50 km, rake is 180.0 (right-lateral slip), slip is 100 cm. The conventions for strike, dip, and rake are the standard ones (e.g., Aki and Richards, 1980, p. 106).]

[The fault plane is represented with 17 x 25 point sources uniformly distributed on the plane.]

along-strike discretization
17
down-dip discretization
25

Explanation of output files:

The first few lines of the output file **tmatrel-post-rec-EX1.gmt** (postseismic displacements at specified receiver locations) are:

0.0000000000000000	3.1745999999999981	-8.2377272					
-2.0000000	0.0000000	5.56773576659561265E-005	4.54461572682330619E-005	-1.29277196E-05			
0.0000000000000000	5.2955519653953029	-8.2377272					
-2.0000000	0.0000000	9.50847334044079234E-005	7.34914490303044263E-005	-2.16601020E-05			
0.0000000000000000	8.8335130782467317	-8.2377272					
-2.0000000	0.0000000	1.62315247163634943E-004	1.17579318461441591E-004	-3.63086838E-05			
0.0000000000000000	14.735187911187120	-8.2377272					
-2.0000000	0.0000000	2.74745778865951348E-004	1.85422442713521632E-004	-6.06737340E-05			
0.0000000000000000	24.579774870395045	-8.2377272					
-2.0000000	0.0000000	4.57565272964112631E-004	2.83959540628751046E-004	-1.00108082E-04			
0.0000000000000000	41.001535665562479	-8.2377272					
-2.0000000	0.0000000	7.44945096034685416E-004	4.08578817037272410E-004	-1.60279669E-04			
0.0000000000000000	68.394683669752155	-8.2377272					
-2.0000000	0.0000000	1.16527355489295719E-003	5.32394887674305208E-004	-2.43485963E-04			
0.0000000000000000	114.08920857114164	-8.2377272					
-2.0000000	0.0000000	1.69072748708167160E-003	6.13905229049785959E-004	-3.42537882E-04			
0.0000000000000000	190.31227010625091	-8.2377272					
-2.0000000	0.0000000	2.19753663813855062E-003	6.10738739345476761E-004	-4.34649031E-04			
0.0000000000000000	317.45999999999992	-8.2377272					
-2.0000000	0.0000000	2.51901085900534810E-003	5.24046124479864259E-004	-4.85738565E-04			

Columns 1 and 2 have the time interval (years) for cumulative displacement.
Columns 3 and 4 have the longitude and latitude of the receiver point in geographic coordinates (degrees), column 5 the (negative of the) depth (km), columns 6-8 the displacements (meters).

The output files **tmatrel-stat-rec-EX1.gmt** (static displacements at specified receiver locations), **visco2pt5d-post_vertp-EX1.gmt** (postseismic displacements on a vertical slice sampling all GLL points on the arc $\phi=0$), and **visco2pt5d-stat_vertp-EX1.gmt** (static displacements on a vertical slice sampling all GLL points on the arc $\phi=0$) have the same format as above.

Note that **tmatrel-post-rec-EX1.gmt** has cumulative displacements (columns 6,7,8 [E, N, Up displacements]) for each of 10 logarithmically-spaced postseismic time intervals at 121 receiver sites -- those in 'receivers-latlondepEX1.txt'. Similarly, **visco2pt5d-post_vertp-EX1.gmt** has cumulative displacements (columns 6,7,8 [E, N, Up displacements]) for each of 10 postseismic time intervals on the profile corresponding to azimuth=0 in model coordinates.

The first few lines of the output file **visco2pt5d-post-phival-EX1.gmt** (postseismic displacements at a set of points on Earth's surface) are:

```

0.00000000000000000000    21.163999999999987    -2.50629500E-06    2.1818237    -2.95065211046126709E-004
-2.10180647981683010E-004 -7.11374450E-05
0.00000000000000000000    42.327999999999975    -2.50629500E-06    2.1818237    -5.84221868944914940E-004
-3.51899745626236724E-004 -1.36562667E-04
0.00000000000000000000    63.491999999999962    -2.50629500E-06    2.1818237    -8.48261863051739343E-004
-4.39412477649400637E-004 -1.91875559E-04
0.00000000000000000000    84.655999999999949    -2.50629500E-06    2.1818237    -1.07907130161221830E-003
-4.91916465879046832E-004 -2.37699205E-04
0.00000000000000000000    105.81999999999995    -2.50629500E-06    2.1818237    -1.27570465865709600E-003
-5.21818561011631421E-004 -2.75417115E-04
0.00000000000000000000    21.163999999999987    -5.28586730E-02    2.1818237    -2.98408562763454442E-004
-2.12876375071288589E-004 -7.18953306E-05
0.00000000000000000000    42.327999999999975    -5.28586730E-02    2.1818237    -5.90841412820479776E-004
-3.56297283418015775E-004 -1.38007701E-04
0.00000000000000000000    63.491999999999962    -5.28586730E-02    2.1818237    -8.57879139256784900E-004
-4.44785128775213100E-004 -1.93900138E-04
0.00000000000000000000    84.655999999999949    -5.28586730E-02    2.1818237    -1.09131332236889395E-003
-4.97820356593609947E-004 -2.40204536E-04
0.00000000000000000000    105.81999999999995    -5.28586730E-02    2.1818237    -1.29018508717692530E-003
-5.27984100742388395E-004 -2.78319174E-04

```

Columns 1 and 2 have the time interval (years) for cumulative displacement.
Columns 3 and 4 have the longitude and latitude of the receiver point in geographic coordinates,
and columns 5-7 the displacements (units are meters).

Note that the observation time interval specified in **source-spherical.paramEX1** (first 21.164 years following the synthetic event) was chosen to be the 1τ postseismic interval, as dictated by the Maxwell viscosity and shear modulus of the sub-lithosphere specified in **elastic.paramEX1-Maxwell**. That is, the time interval (t_1 , t_2) corresponds to cumulative displacements up to 1τ years following the slip event. This was chosen for this example so that the displacements in **visco2pt5d-post-phival-EX1.gmt** correspond to multiples of the first 1τ postseismic interval, i.e. the five output time intervals are (0, 1τ), (0, 2τ), (0, 3τ), (0, 4τ), and (0, 5τ).

Plots

The figures below are comparisons between the visco2pt5d solutions (from output file **visco2pt5d-post-phival-EX1.gmt**) and the semi-analytic solution from viscoelastic mode summation (Pollitz, 1997). The figures correspond to Figures 6-8 of Pollitz (2014).

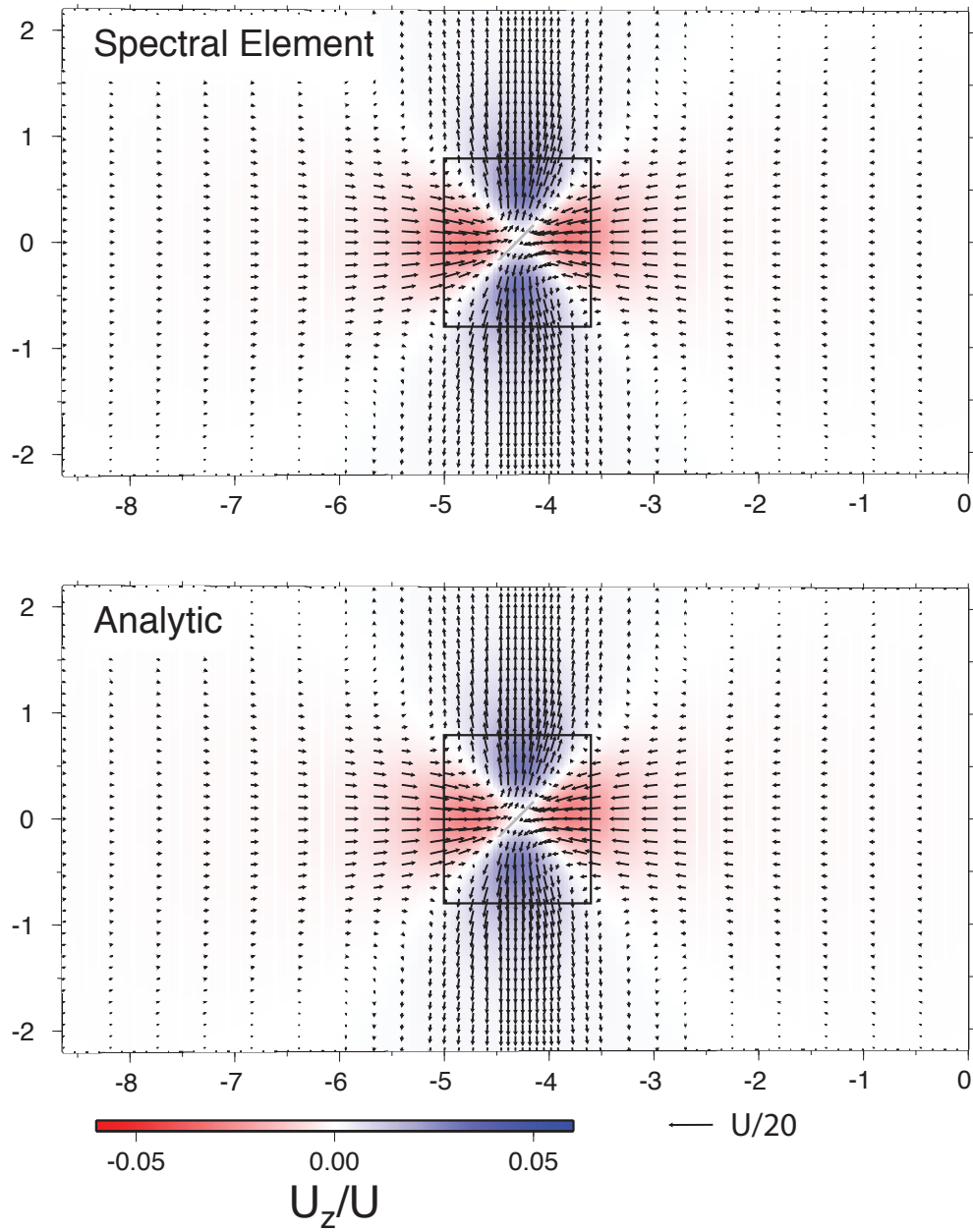


Figure 7. Horizontal displacements (arrows) and vertical displacements (color shading) for relaxation following strike-slip faulting on the fault plane indicated with the white rectangle. These are cumulative displacements up to 5τ years following the slip event, where τ is the material relaxation time of the ductile substrate. The color scale indicates the ratio of vertical displacement U_z to fault slip U . Black rectangle indicates the area plotted in Figure 8.

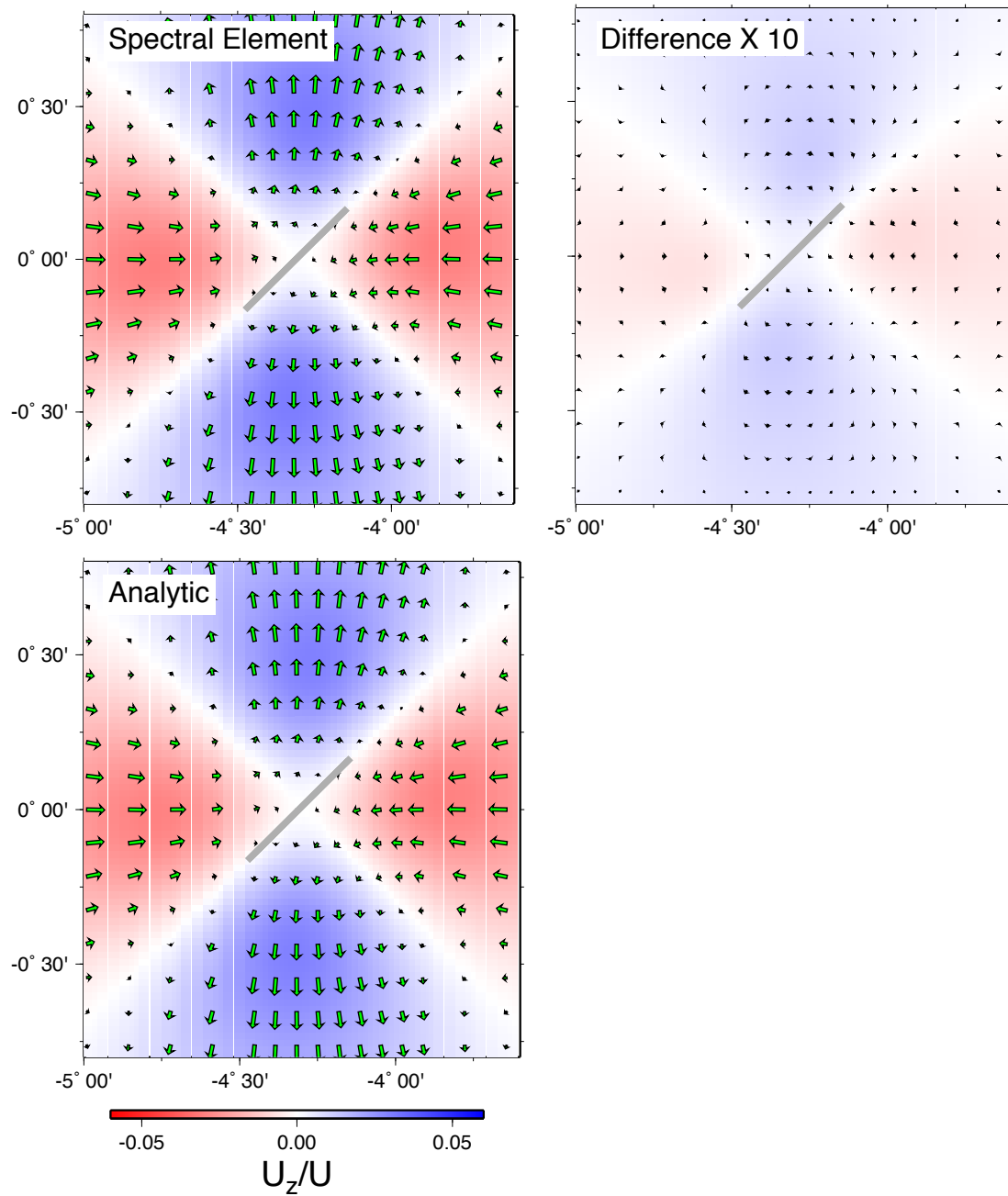


Figure 8. Close-up view of the motions following strike-slip faulting shown in Figure 7. Right-hand plot shows difference between SEM and analytic displacement fields.

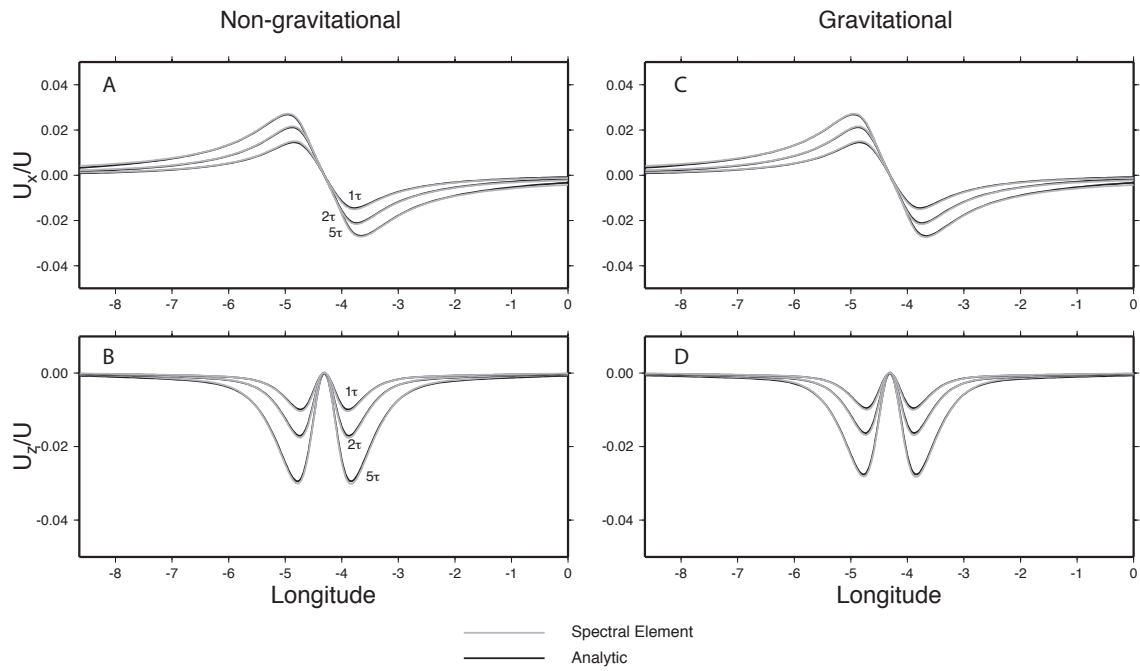


Figure 9. Ratio of horizontal displacement U_x (a,c) and vertical displacement U_z (b,d) to fault slip U for displacements following strike-slip faulting at times 1τ , 2τ , and 5τ along the equator of the area shown in Figure 7. Non-gravitational displacements from the spectral element and analytic methods are compared in a,b, and gravitational displacements in c,d.

5.2 Example 2

This example will replace the laterally homogeneous structure of Example 1 with a laterally variable structure. As in Example 1, this example evaluates post-strike-slip faulting displacements generated by a 50 km-long vertical fault occupying the lower portion of the elastic layer on a spherically-layered model. This model has a prescribed Maxwell viscoelastic asthenosphere below an elastic lithosphere. The change from Example 1 is that the lithosphere thickness has a step increase from 30 km to 100 km in the middle of the model domain.

To run this example, run the command file 'example2.x', which has the same structure as 'example1.x' of section 5.1, but with one different input file. This is exemplified by the first few lines of 'example2.x'

```
#!/bin/bash
#
export VISCODIR=/home/cig/VISCO2.5D
export EXDIR=$VISCODIR/MAINPROG
export WORKDIR=$VISCODIR/Work
export WORKDIR1=$VISCODIR/Work1
#
cp elastic.paramEX2 $WORKDIR/elastic.param
cp simulation-spherical.infoEX2 $WORKDIR/simulation-spherical.info
cp source-spherical.paramEX2 $WORKDIR/source-spherical.param
cp $EXDIR/visco2pt5d $WORKDIR/.
```

The input file **simulation-spherical.infoEX2** is identical to **simulation-spherical.infoEX1**, and the input file **source-spherical.paramEX2** is identical to **source-spherical.paramEX1**. The only difference with respect to Example 1 is the viscoelastic structure. The structure prescribed in the file **elastic.paramEX2** has pointwise values of seismic velocities and Maxwell solid parameters with the format

theta (deg.)	r-6371. (km)	Vp (km/s)	Vs (km/s)	Rho (g/cm ³)	\mu' (10 ^{10} Pa)	\eta_2 (10 ^{18} Pa s)	\eta_1 (10 ^{18} Pa s)
4.1000	-101.6098	5.4772	3.1623	3.0000			0.100000E+02
4.1000	-100.0100	5.4772	3.1623	3.0000			0.100000E+02
4.1000	-99.9900	5.4772	3.1623	3.0000			0.100000E+12
4.1000	-98.5904	5.4772	3.1623	3.0000			0.100000E+12
..							
..							
4.1872	-31.4096	5.4772	3.1623	3.0000			0.100000E+02
4.1872	-30.0100	5.4772	3.1623	3.0000			0.100000E+02
4.1872	-29.9900	5.4772	3.1623	3.0000			0.100000E+12
4.1872	-29.3902	5.4772	3.1623	3.0000			0.100000E+12

Between 4.1000 and 4.1872 degrees from the edge of the model domain, the lithosphere thickness jumps from 100 km to 30 km, as shown in Figure 10.

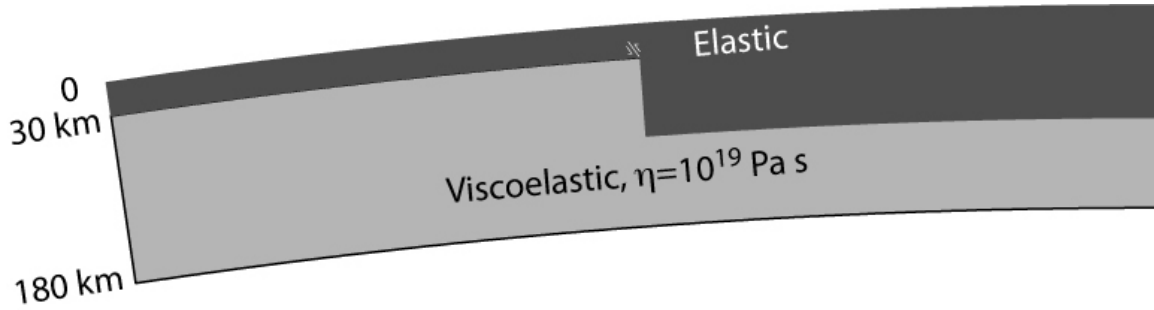


Figure 10. Laterally heterogeneous model used in Example 2.

Plots

The figures below are comparisons of surface displacements between the visco2pt5d solutions of Example 1 and Example 2. They are derived from the output files **visco2pt5d-post-phival-EX1.gmt** and **visco2pt5d-post-phival-EX1.gmt**, respectively. These are almost identical to Figures 13 and 14 of Pollitz (2014), but the published figures include gravitation and the present examples do not.

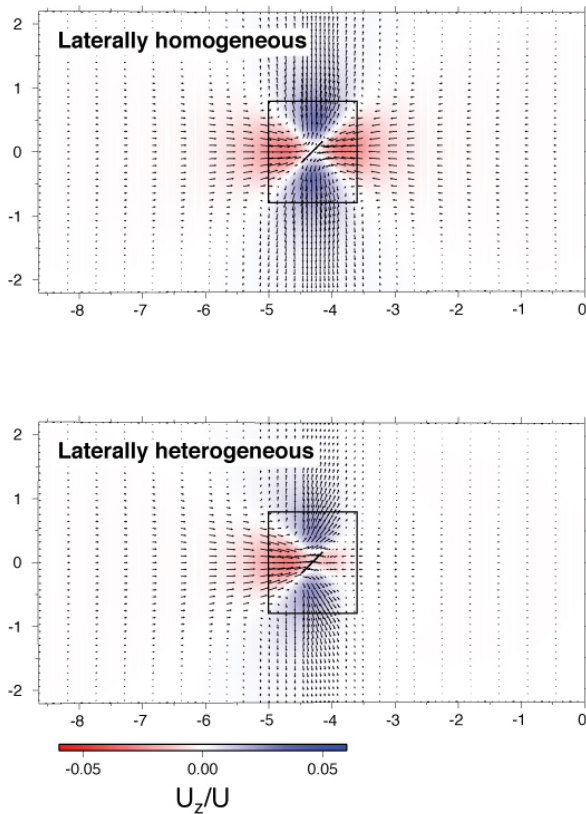


Figure 11. Horizontal displacements (arrows) and vertical displacements (color shading) for viscoelastic-gravitational relaxation following strike-slip faulting on the fault plane indicated with the black line. These are cumulative displacements up to 5τ following the slip event. The color scale indicates the ratio of vertical displacement U_z to fault slip U . The two plots compare the

displacement fields on the laterally homogeneous (Example 1) and heterogeneous (Example 2) models.

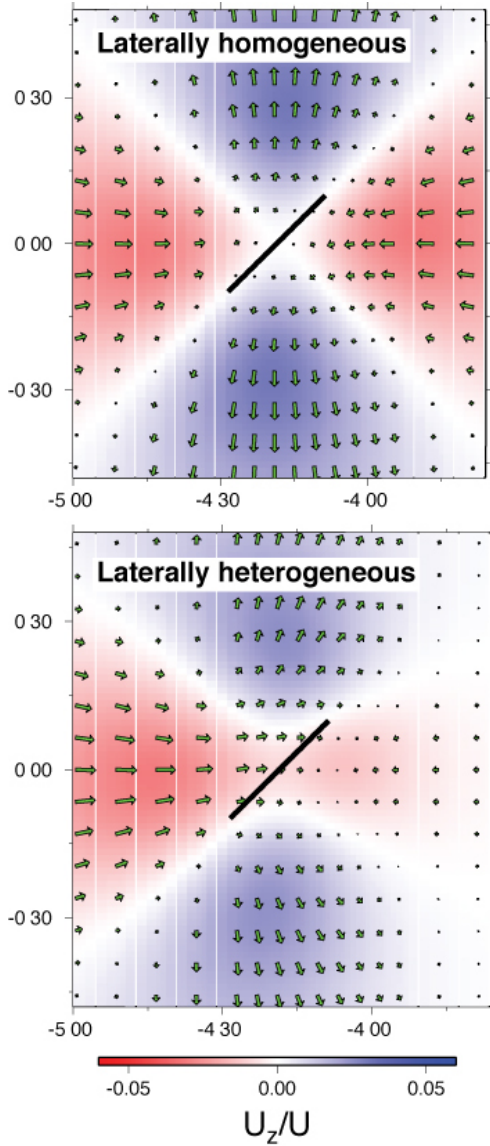


Figure 12. Zoomed-in view of the motions following strike-slip faulting shown in Figure 11.

5.3 Example 3

In this example we calculate cumulative postseismic motions following the 1999 M7.1 Hector Mine earthquake using the 2D viscoelastic structure obtained by Pollitz (2015). The viscoelastic model has a prescribed Burgers-body viscoelastic asthenosphere below an elastic lithosphere, and at mantle depths there is a discontinuity in (transient and steady-state) viscosities across a NW-SE trending boundary that divides the western and central Mojave Desert.

To run this example, run the command file `example3.x`, which has the same structure as `example1.x` of section 5.1, just with a different set of input files. This is clear from the first few lines of `example3.x`

```
#!/bin/bash
#
export VISCODIR=/home/cig/VISCO2.5D
export EXDIR=$VISCODIR/MAINPROG
export WORKDIR=$VISCODIR/Work
export WORKDIR1=$VISCODIR/Work1
#
cp elastic.paramEX3 $WORKDIR/elastic.param
cp simulation-spherical.infoEX3 $WORKDIR/simulation-spherical.info
cp source-spherical.paramEX3 $WORKDIR/source-spherical.param
cp $EXDIR/visco2pt5d $WORKDIR/.
```

Explanation of input files:

(1) Annotated version of **simulation-spherical.infoEX3** (refer to Figure 13)

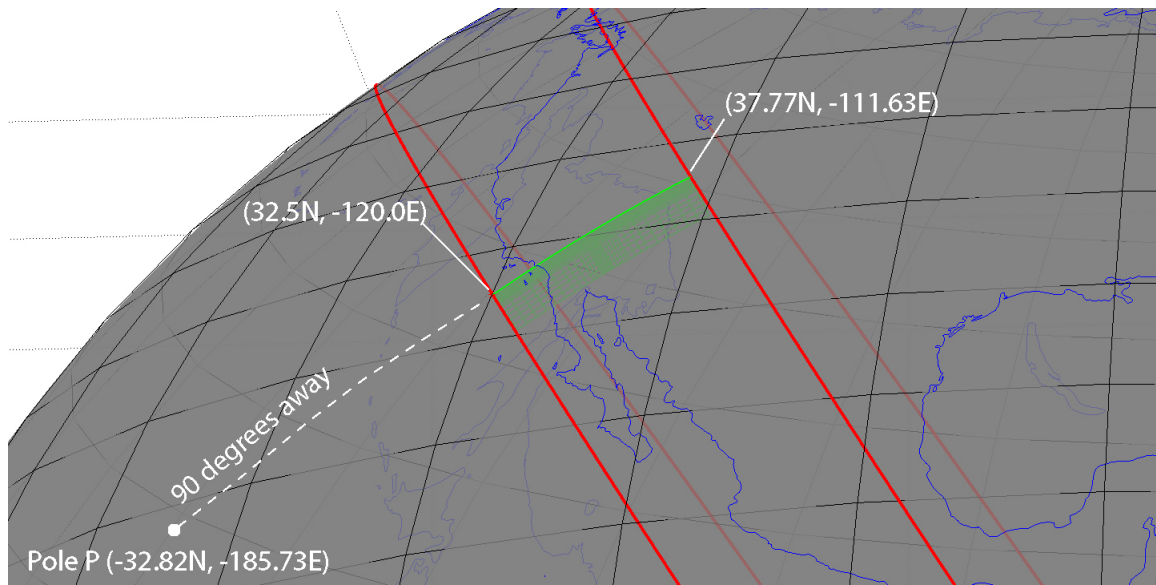


Figure 13. 2D model domain (in green) and geometry specified in **simulation-spherical.infoEX3**.

[The model domain is essentially bounded by two small circles centered on a pole prescribed by the first two input lines (as well the radial dimension as prescribed in input lines 5-6). In this file the pole is located 90 degrees away from (32.5N,-120.0E) at an azimuth of 230 deg. from that point. This pole turns out to be located at P=(-32.82N,-185.73E).]

geographic coordinates of (theta,phi)=(theta_ref,0.) of spherical geometry in (deg.,deg.)

32.5 -120.0

Angular distance theta_ref (geocentric deg.) and azimuth (deg. CW from due N) of pole from the above point

90. 230.

number of cells in theta^-direction

34

0.0000	-216.0000	8.4685	4.5421	3.3930	3.5000	0.240000E+01	0.100000E+02
0.0000	-213.4399	8.4685	4.5421	3.3930	3.5000	0.240000E+01	0.100000E+02
..							
..							
5.6702	-218.5601	8.4573	4.5361	3.4020	0.0000	0.100000E+03	0.100000E+14
5.6702	-216.0000	8.4573	4.5361	3.4020	0.0000	0.100000E+03	0.100000E+14
5.6702	-216.0000	8.4685	4.5421	3.3930	3.5000	0.400000E+01	0.400000E+02
5.6702	-213.4399	8.4685	4.5421	3.3930	3.5000	0.400000E+01	0.400000E+02

This viscoelastic structure is discontinuous across a vertical boundary shown below]

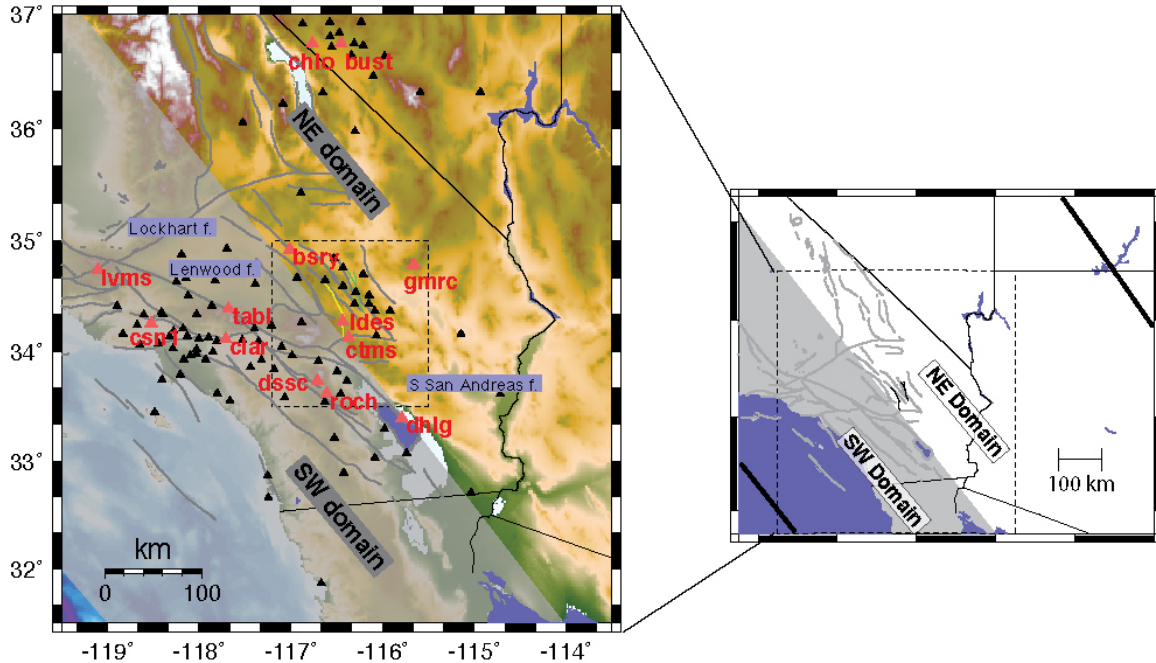


Figure 14. Definition of two structural domains in southern California having different vertical stratification of viscoelastic properties. Triangles show locations of GPS stations modeled by Pollitz (2015). Yellow and green lines denote the traces of the 1992 Landers and 1999 Hector Mine earthquake ruptures, respectively. The horizontal boundaries of the model domain are shown in the right-hand figure as thick black lines. Modified from Figure 1 of Pollitz (2015).

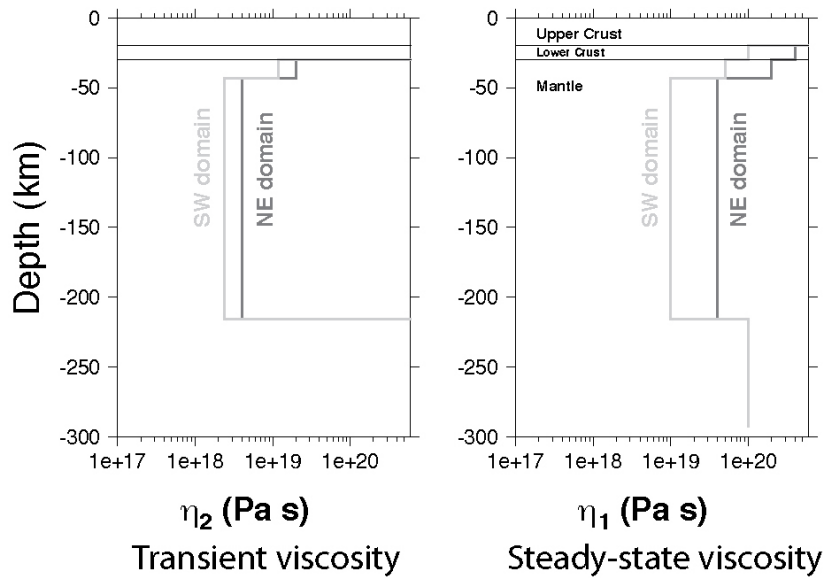


Figure 15. Depth-dependent transient (left-hand side) and steady-state (right-hand side) viscosity as a function of depth in the two domains. These structures are prescribed by visco2pt5d input file **elastic.param** (linked to **elastic.paramEX3**). Modified from Figure 9 of Pollitz (2015).

elastic.param

gravitational acceleration at earth's surface (m/s²) (0 for non-gravitational case)

[In computations without gravitation, this is set to 0; in computations with gravitation, this is set to 9.8]

0.

Plots

The figure below is derived from the output file **visco2pt5d-post_vertp-EX3.gmt**

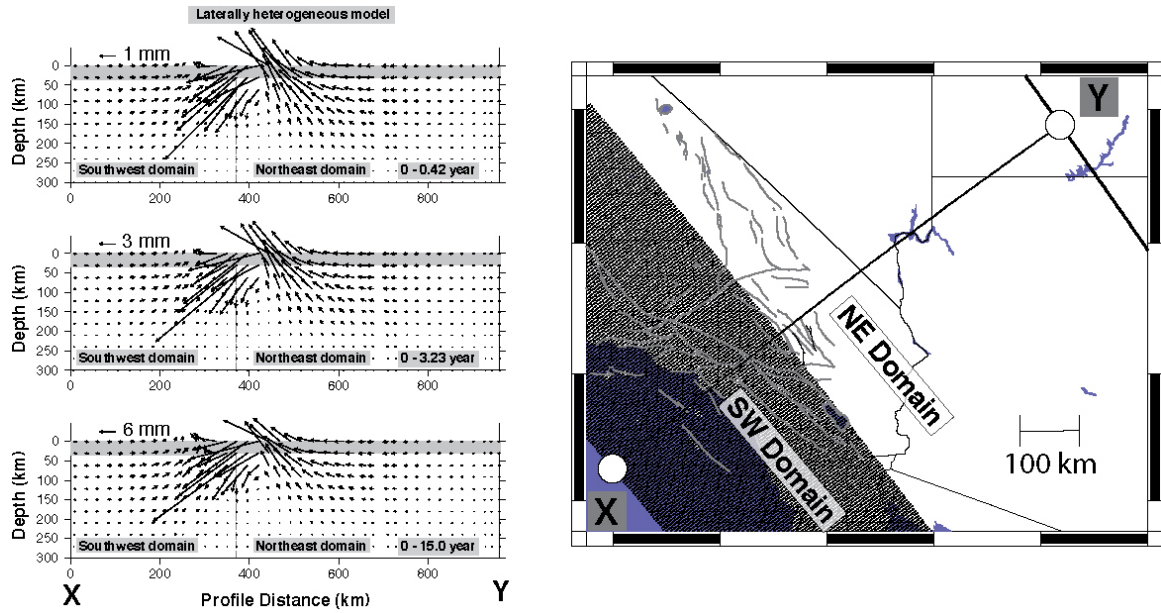


Figure 16. Cumulative post-Hector Mine displacements for the indicated time periods resolved onto a vertical plane with surface trace shown in the right-hand figure. These displacements are calculated on the 2D viscoelastic structure of Figures 12 and 13. Shaded region delineates the crust. Modified from Figure S7 of Pollitz (2015).

The figure below is the coseismic displacement field. It is plotted from the output file **visco2pt5d-stat-rec-EX3.gmt**

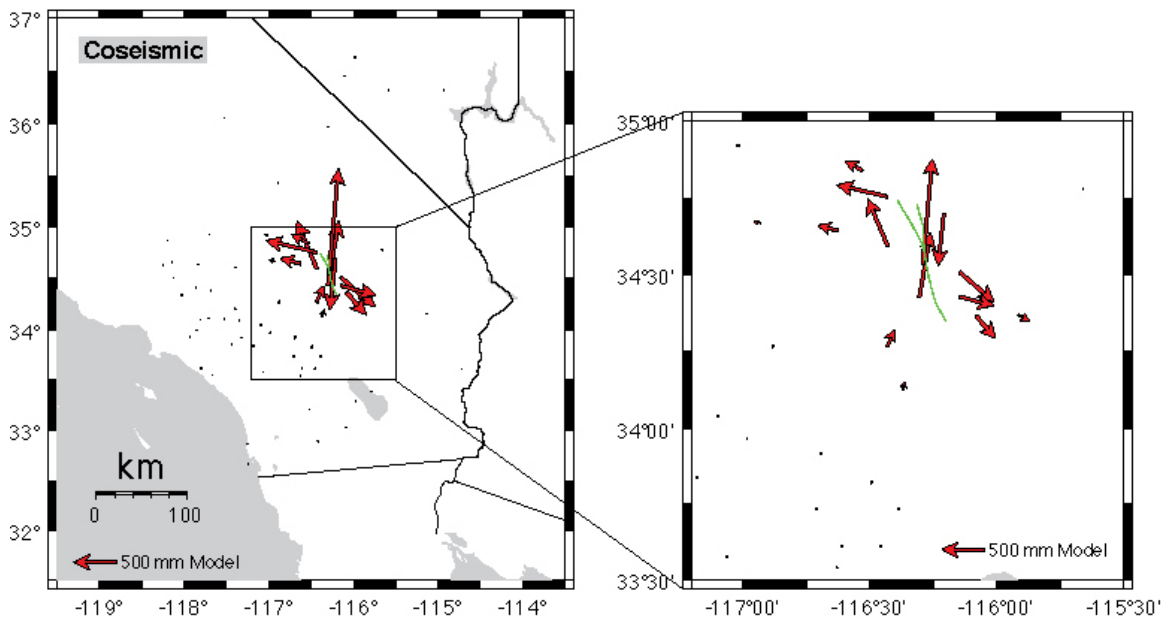


Figure 17. Coseismic displacement field at selected GPS sites for the Hector Mine earthquake generated by 'example3.x'.

The figure below is the 0 – 15 years postseismic displacement field. It is plotted from the output file **visco2pt5d-post-rec-EX3.gmt**

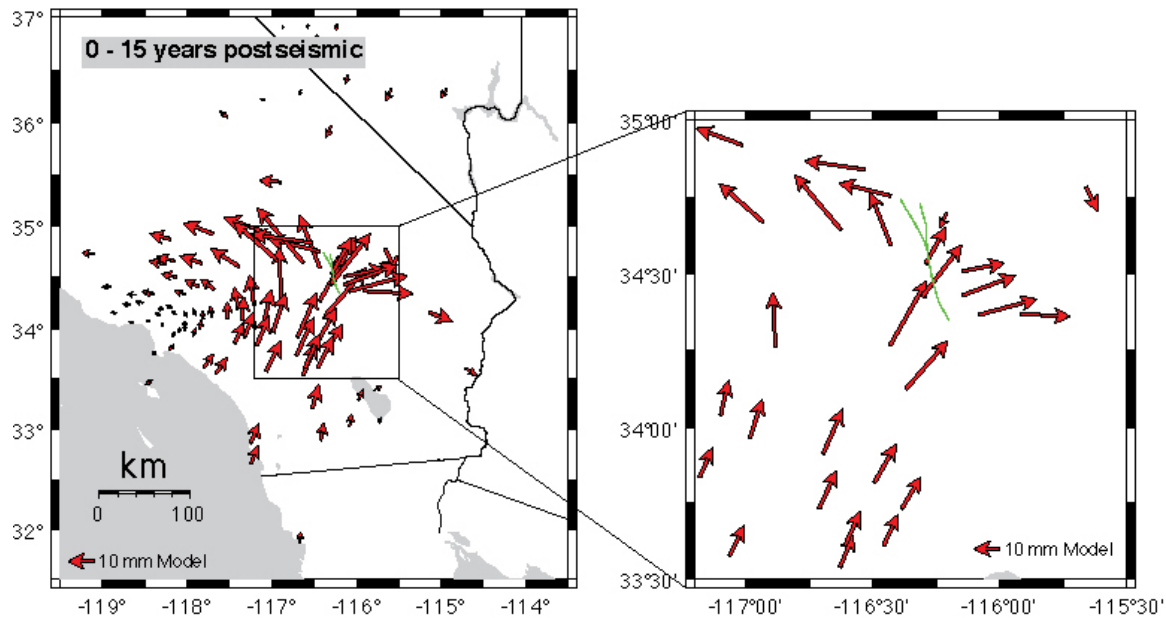


Figure 18. Postseismic displacement field at selected GPS sites for the Hector Mine earthquake generated by 'example3.x'.

6 Practical considerations

- As described in section 5.1 (*"Explanation of 'example1.x'"*) visco2pt5d is typically run three times in sequence. The first run uses information from **simulation-spherical.info** to obtain indexing arrays of GLL points on the global grid. Once this is done, the second and third runs determine displacements in the Laplace transform domain and time domain, respectively, using additional input files **elastic.param** and **source-spherical.param**, which are linked to specific input files in the examples of section 5. However, if the lines specifying the number of cells in the θ -direction and z -direction in **simulation-spherical.info** do not change, then the first run of visco2pt5d need not be repeated. The second and third runs can be repeated with other linked files **elastic.param** and **source-spherical.param** without having to re-determine the indexing arrays.
- In the source programs (VISCO2.5D/SOURCE/) 'visco2pt5d.f' and 'visco2pt5dsubs.f', parameters NCMAZ and NCMAZ specify the maximum expected values of the "number of cells in θ -direction" and "z-length of each cell (km)" input in **simulation-spherical.info**. The present values of NCMAZ and NCMAZ are set at 37, i.e.


```
parameter (ncmax=37)
parameter (ncmaz=37)
```

If a greater number of cells in the horizontal (i.e. θ) or vertical (i.e. z) directions are intended, then these parameter values should be increased within the source files (and those two lines appear several times...) and then visco2pt5d should be re-compiled.

- The "Effective width of third (i.e. ϕ) dimension (km)" specified in **simulation-spherical.info** is the spacing between assumed repeating sources, i.e. identical sources are evenly spaced along model azimuth ϕ . This spacing was chosen to be 1200 km in both examples of section 5, large enough to not affect the solution in the areas being analyzed, which are restricted to relatively small ϕ . The computation time of visco2pt5d is inversely proportional to the value of this spacing. It is the user's judgement (or tests with different spacings could be done) to choose this spacing bearing in mind the tradeoff

- between accuracy and speed of the computation.
- The cell sizes in the horizontal and vertical dimensions are specified in the “theta-length of each cell (radians)” and “z-length of each cell (km)” array entries in **simulation-spherical.info**. (The theta-length values in radians can be multiplied by the radius of the earth (6371 km) to translate them into horizontal cell sizes in km.) These lengths should be smallest in the near-source region and may be larger at farther distance from the source. The postseismic displacement field at earth’s surface is expected to be of wavelength equal to the elastic layer thickness or greater – the elastic layer thickness in the near-source region and greater at farther distance from the source. The postseismic displacement field at depth generally may be of wavelength equal to the distance of a given observation depth from the base of the elastic layer (depending also how deep the model source extends). In the case that postseismic deformation near the base of the elastic layer is desired, smaller horizontal and vertical cell sizes would be required in the near-source region.
 - The “minimum wavelength in third dimension (km)” specified in **simulation-spherical.info** is the minimum wavelength involved with the m-summation in equations 1 and 2. For postseismic deformation at earth’s surface, it should be set to approximately the elastic layer thickness or less (30 km in Examples 1 and 2; 20 km in Example 3).
 - The most time-consuming part of the computation is the computation of Laplace-transformed displacements done in the second run of visco2pt5d (out of the total three runs) in the examples. The code has been designed to be run trivially in parallel by telling visco2pt5d in standard input what fraction of the considered Laplace transform parameters are to be done. A variation on ‘example1.x’ – ‘example1-2proc.x’ repeats Example 1 but assigns one-half of the computation to one process and the other half to another process, thereby cutting down the computation time of this step by a factor of 2 (assuming the computer has at least two cores). ‘example1-2proc.x’ will produce identical output to ‘example1.x’.